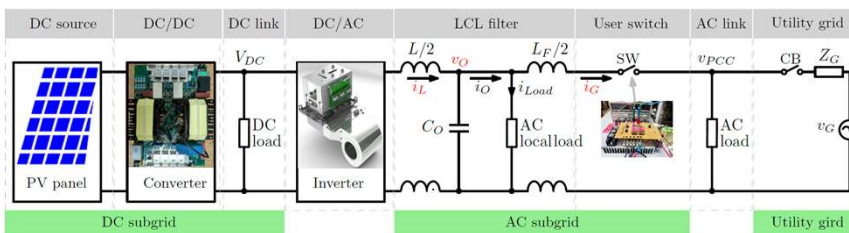


# Large-Bandwidth Triple-Loop Control of Grid-Connected Inverters

## 1. Abstract

A large-bandwidth, triple-loop controller designed for single-phase, grid-tied inverters is analyzed. This organization provides several benefits, including a regulated local ac voltage, a large-bandwidth control of the injecting power and a good robustness against different types of grid perturbations. Besides, the proposed controller is inherently able to guarantee seamless transitions between grid-tied and islanded operation, showing good potential for application to nano- and micro-grid utility interface converters.

## 2. System configuration

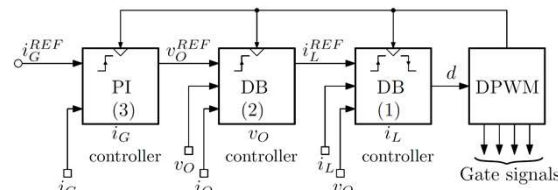


Symbol	Value
$V_{DC}$	450 V
$f_{sw}$	20 kHz
$L$	1.4 mH
$ESR_L$	60 mΩ
$C_o$	30 μF
$L_F$	0.55 mH
$ESR_{L_F}$	75 mΩ
$S_o$	3 kVA
$V_G$	230 V

## 3. Control strategy

- **Inductor current loop** (deadbeat controller) provides satisfying system damping and rapid overcurrent protection.
- **Output voltage loop** (deadbeat controller) guarantees seamless mode transitions and high-quality local-voltage supply.
- **Grid current loop** (PI controller) can be designed with relatively large bandwidth. This is crucial to attain good harmonic attenuation and resilience to grid perturbations.

## 4. Large-bandwidth triple-loop controller



Structure of the proposed triple-loop controller

Control equations of each loop:

$$d = \frac{L f_{sw}}{V_{DC}} \cdot [i_L^{REF} - i_L] + \frac{v_O}{2V_{DC}} + \frac{1}{2} \quad (1)$$

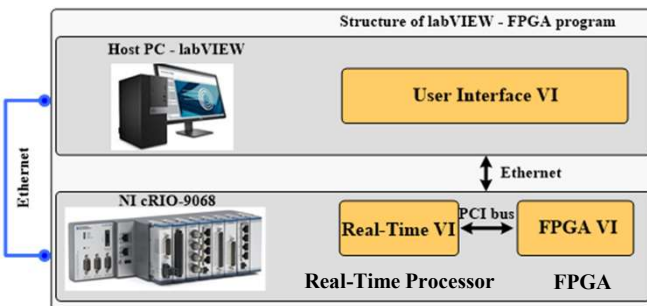
$$i_L^{REF} = C_o f_{sw} \cdot [v_O^{REF} - v_O] + i_O \quad (2)$$

$$v_O^{REF} = H_{PI} \cdot (i_G^{REF} - i_G) \quad (3)$$

## 5. Achieved advantages

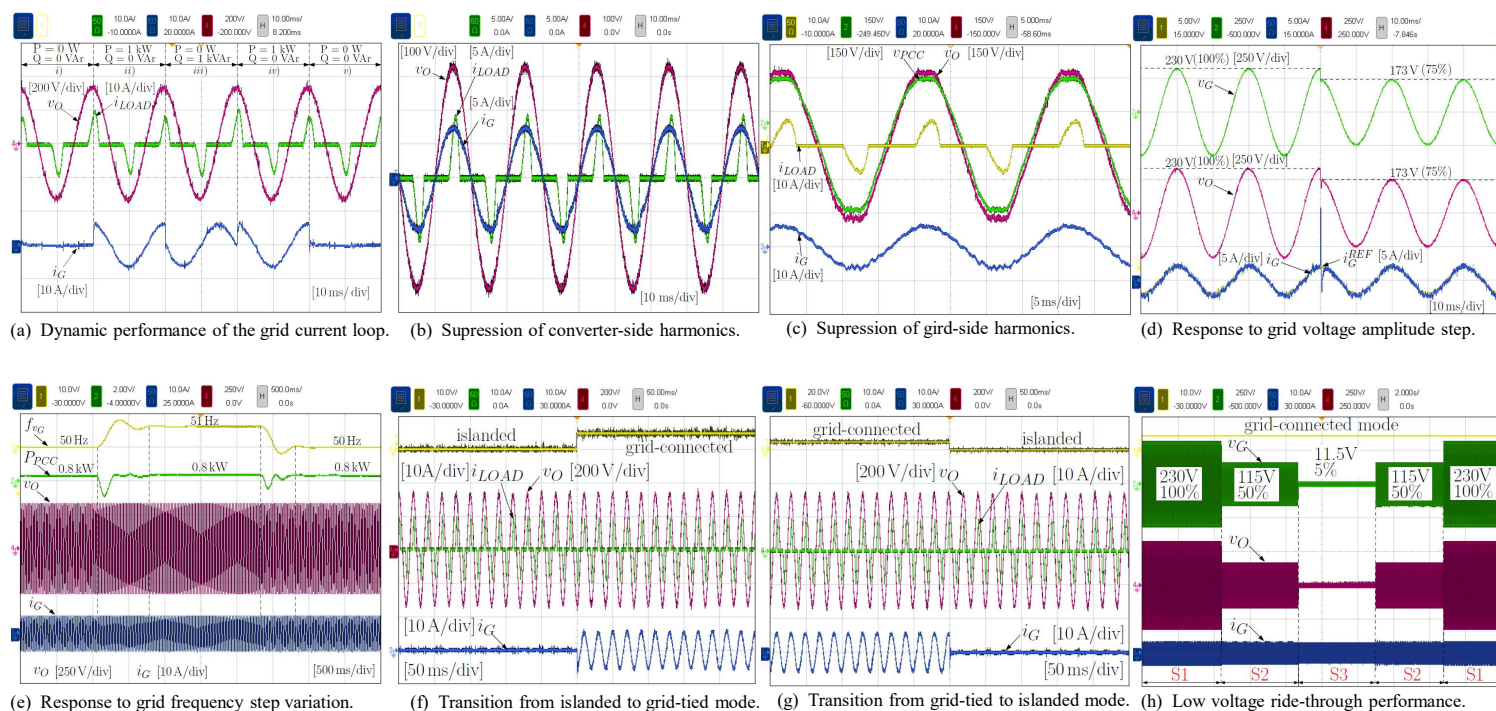
- excellent reference tracking performance.
- a strong attenuation of converter-side and grid-side harmonics.
- grid-connected and islanded operations and seamless transitions between the two.
- robust stability in the presence of grid perturbations (grid voltage harmonic pollution, amplitude and frequency fluctuations or connection impedance parameter variations).

## 6. Implementation of the proposed controller



- **labVIEW:** access and integrate all the components of the cRIO; provides the operator with graphical human machine interface(HMI).
- **Real-Time processor:** provides reliable, predictable behaviour and excels at floating-point math and analysis.
- **FPGA:** excels at high-speed logic and precise timing.

## 7. Experimental verification



## 8. Future work

- Auto-tuning of the grid current loop.
- Top level control scheme of the hybrid AC/DC micro grid.

## 9. Acknowledgments

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